

Experimental characterization of electrodeless plasma thrusters for very low Earth Orbit applications

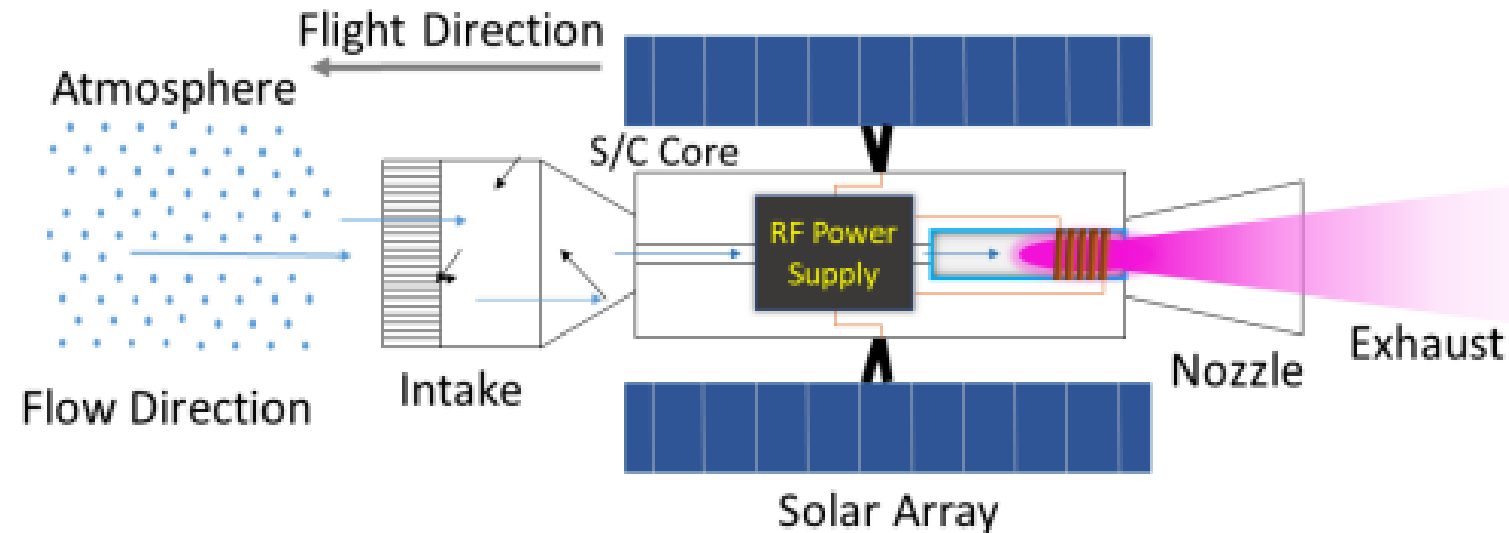
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Supervisors: Jaume Navarro-Cavallé & Pablo Fajardo Peña

PhD Doctoral Meetings 2025. PhD program in Aerospace Engineering UC3M

Introduction to ABEP

➤ Air-Breathing Electric Propulsion (ABEP)



Romano, F. et al. (2017). Performance Evaluation of a Novel Inductive Atmosphere-Breathing EP System.

Advantages of HPT over HT

- No need for cathode or neutralizer.
- Typically operated at lower power.

Disadvantages of HPT over HT

- Less mature technology.
- Lower efficiencies, poor propellant utilization...

Introduction to ABEP

➤ Thesis objectives

Objectives

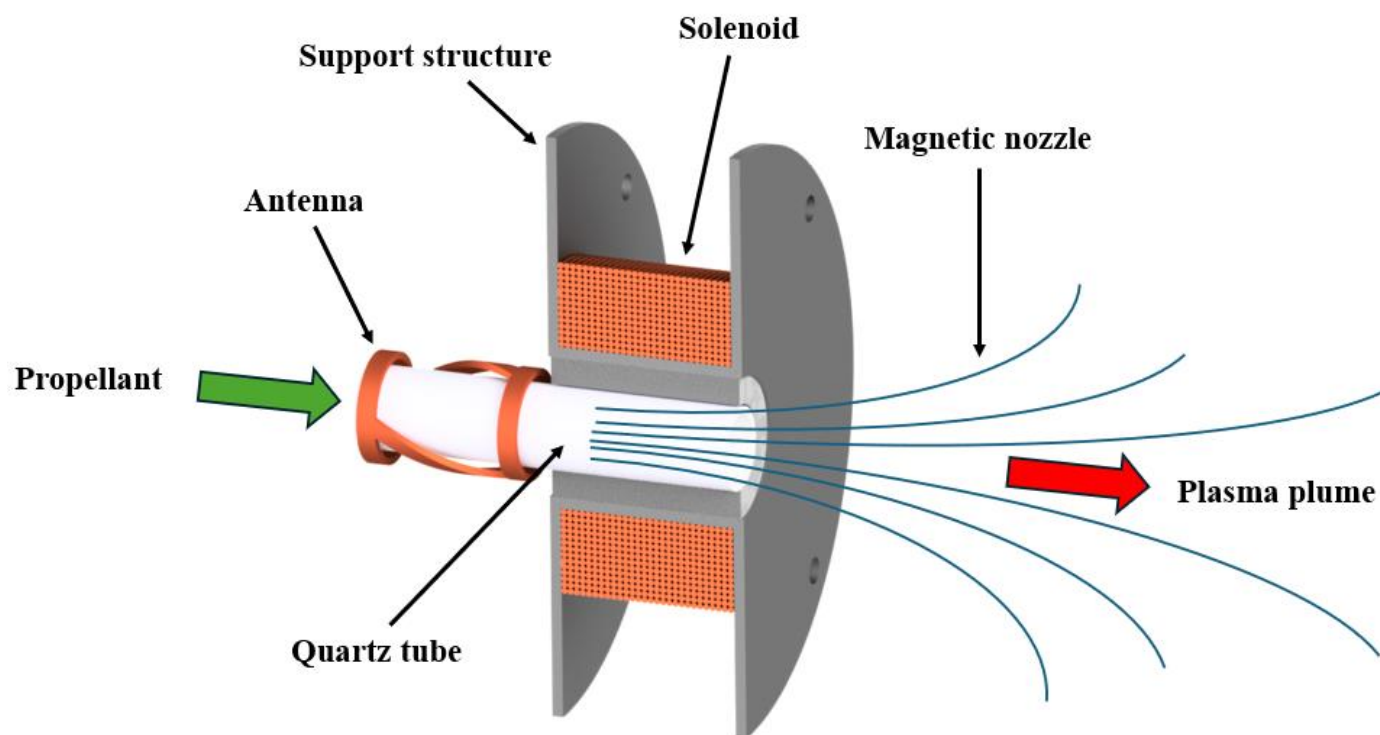
- Experimental analysis of alternative propellants in a **plasma thruster breadboard model**.
 - Characterization of the HPT operated with Air and Air-Kr mixtures.
- Experimental analysis of alternative propellants in a **plasma source breadboard model**.
 - Controlled RF discharges with air mixtures for ABEP validation, and ABEP-Kr assisted validation.
 - Design and improvement of plasma diagnostics for Air / Kr RF plasma.



**Design modifications
and ABEP-oriented
optimization**

Experimental setup

- HPT05M breadboard model jointly developed by SENER Aeroespacial and UC3M



| HPT05M | |
|---------------------------|---------------------|
| Dimensions (diam, length) | 25mm, 140mm |
| RF frequency | 13.56 MHz |
| Power | 300-450 W |
| Magnetic field | 600-1200 G |
| Mass flow rate | 4.5 – 22.5 sccm Air |

Experimental setup

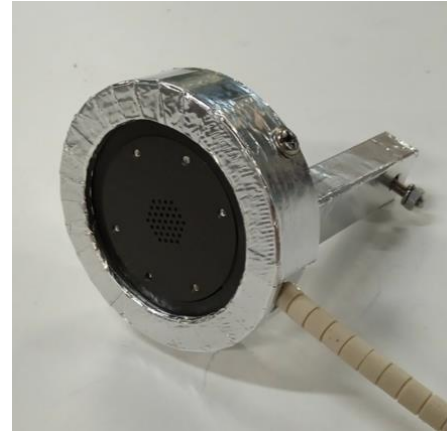
➤ Electrostatic probes

Faraday cup

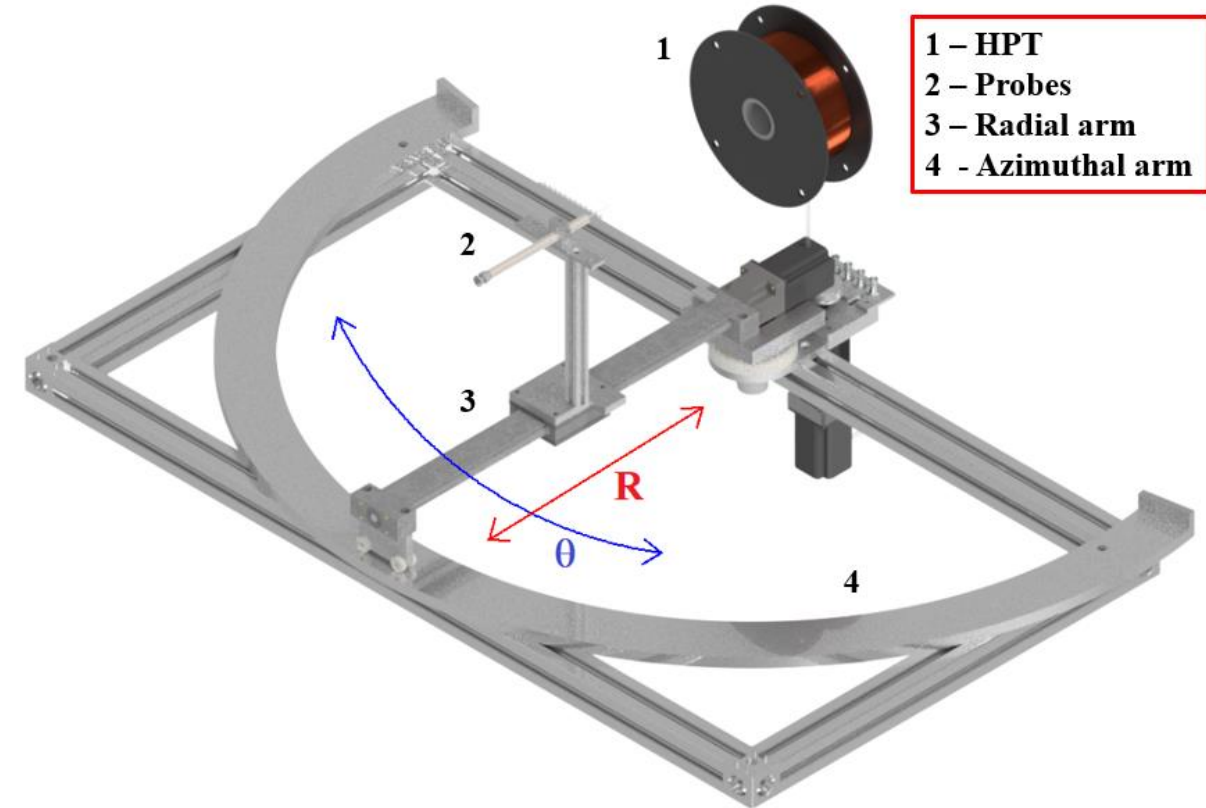


- In-house developed.
- 10 mm aperture.
- Biased at -150 V.

Retarding potential analyzer



- Semion unit by Impedans.
- 4 grids (floating, -60V, 0-250V, -70V).
- Electrode collector at -60V

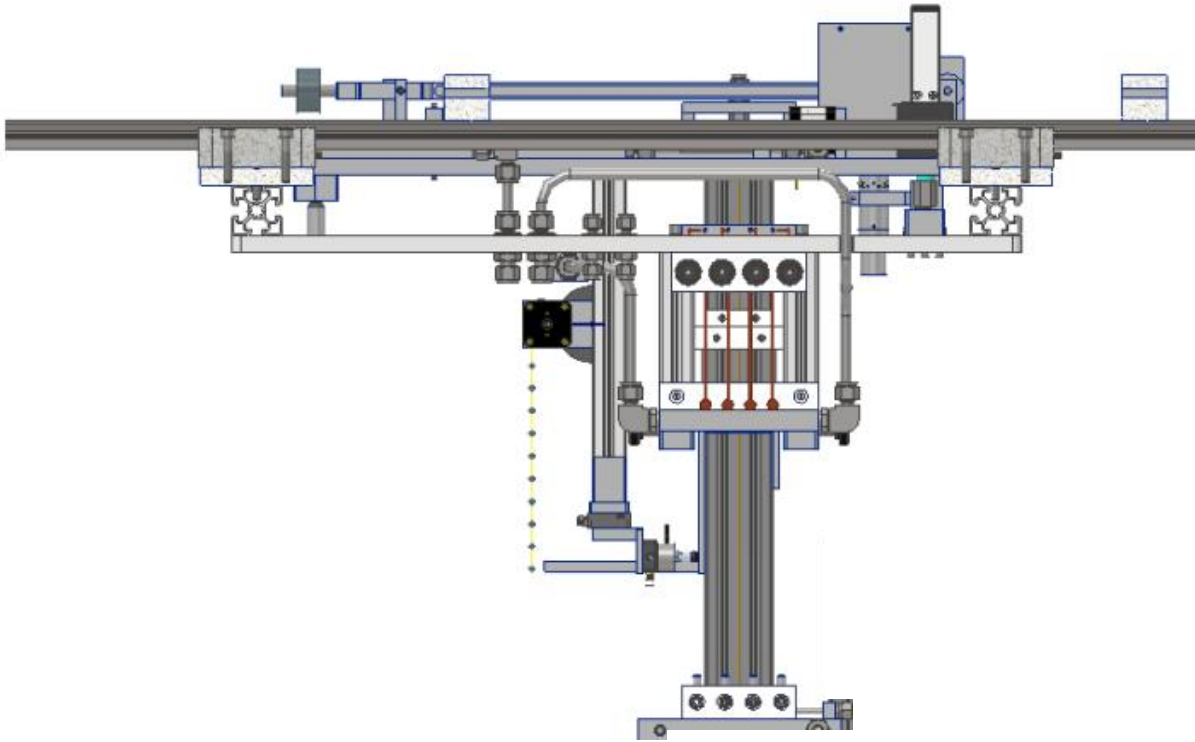


- 1 – HPT
- 2 – Probes
- 3 – Radial arm
- 4 – Azimuthal arm

$$R \in (0, 400) \text{ mm}$$
$$\theta \in (-90, 90) \text{ deg}$$

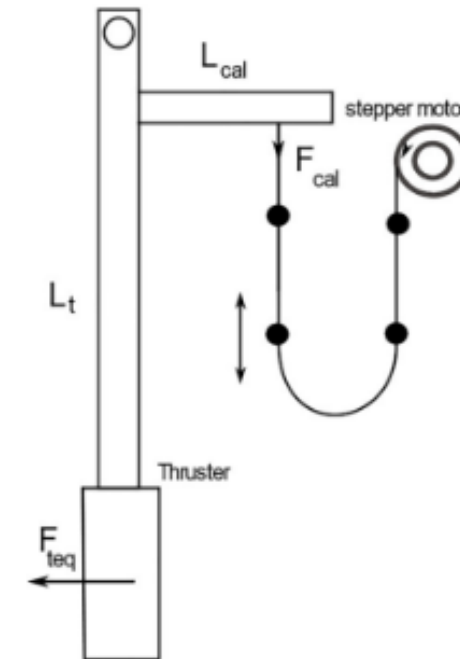
Experimental setup

➤ Thrust balance



Inchingolo M. R, et al. (2022). Direct Thrust Measurements of a circular waveguide Electron Cyclotron Resonance Thruster

$$F_{TB} = \frac{L_{cal}}{L_t} k_{cal} y = \kappa_s y$$



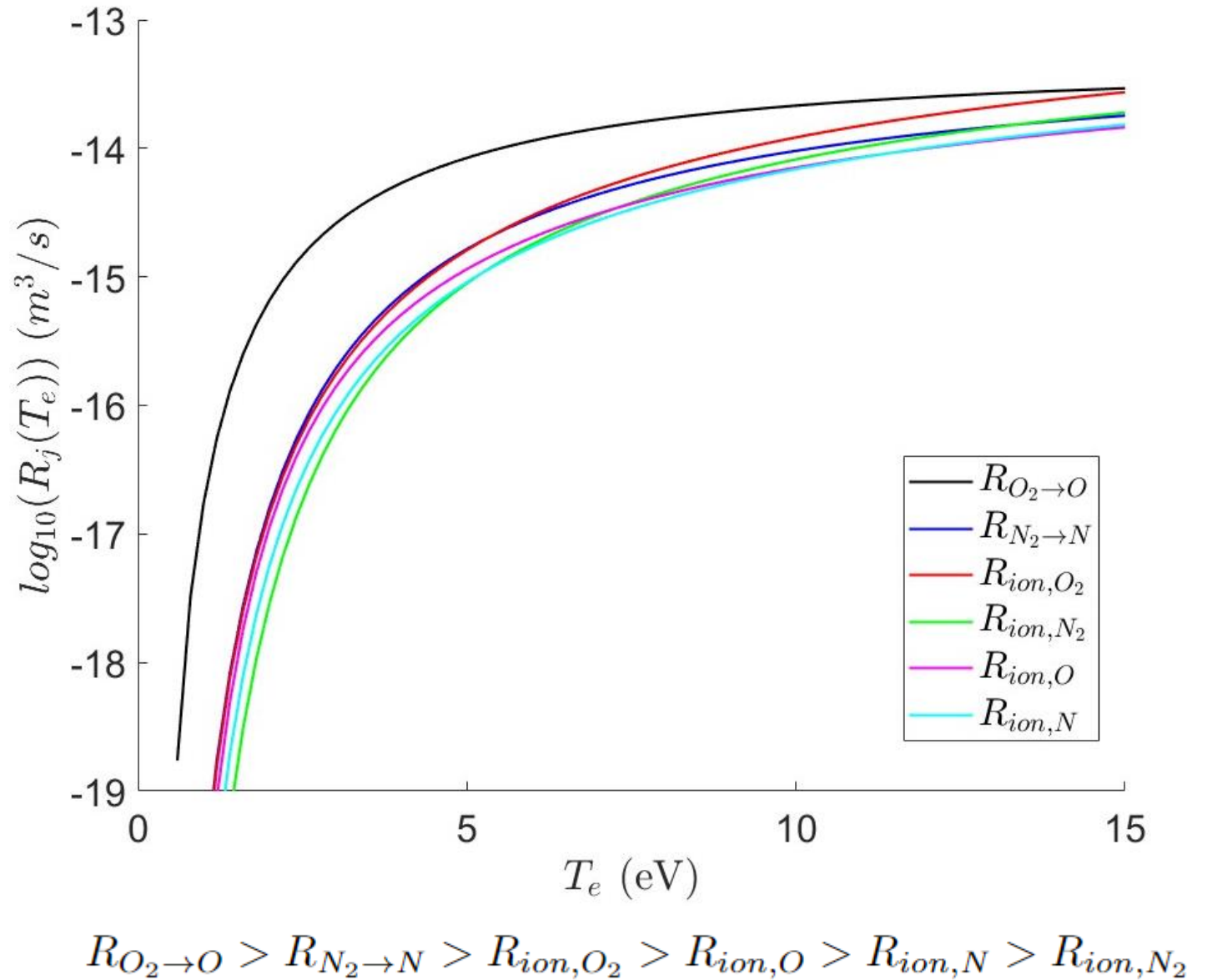
Plume composition impact

➤ Assumptions on the plume composition

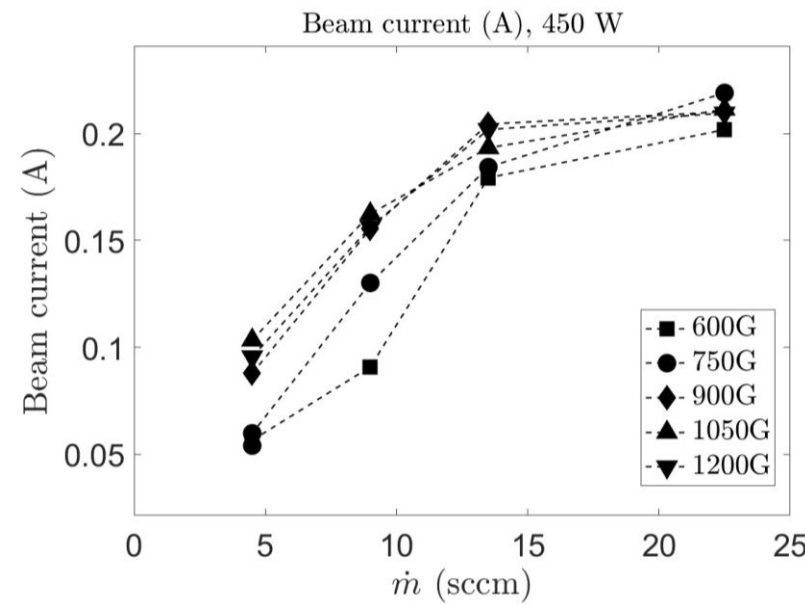
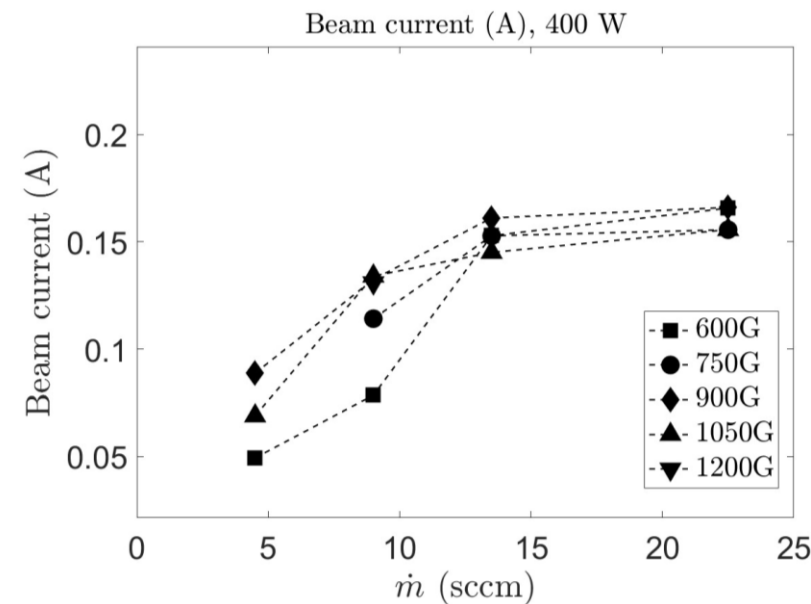
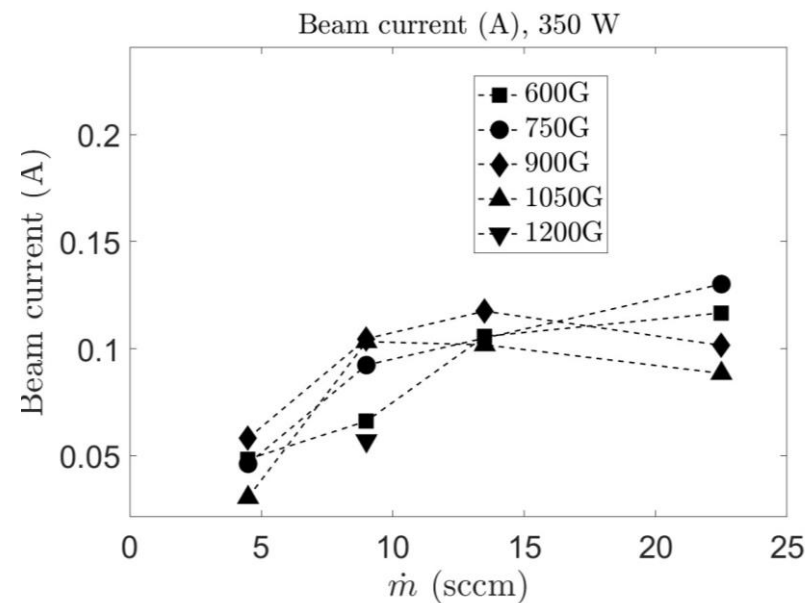
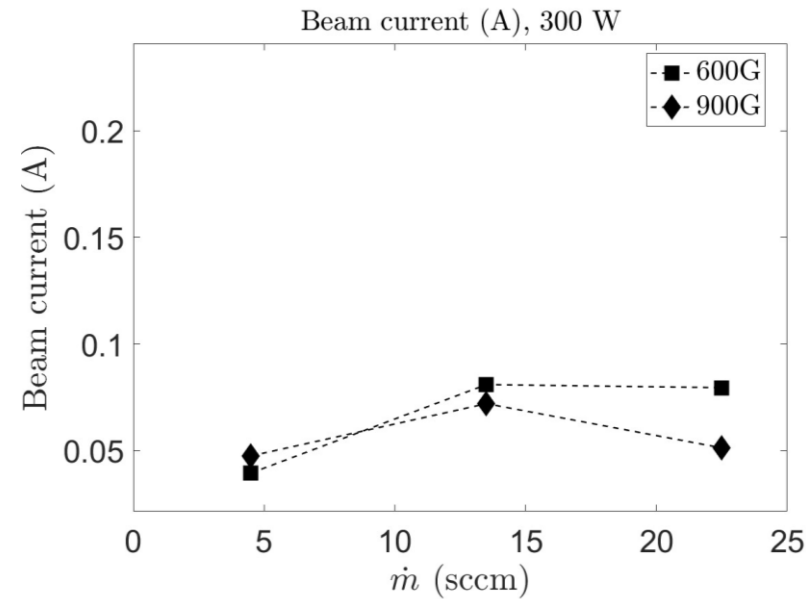
$$\eta_u = \frac{I_b m_i}{\dot{m}} \quad m_i = \sum_j \chi_j (\beta_{O_2}, \beta_{N_2}) m_j$$

| Scenario | m_i (Da) |
|--|------------|
| Full dissociation, $\beta_{O_2} = \beta_{N_2} = 1$ | 14.42 |
| Null dissociation, $\beta_{O_2} = \beta_{N_2} = 0$ | 28.84 |
| $\beta_{O_2} = 1, \beta_{N_2} = 0$ | 23.83 |
| $\beta_{O_2} = 0, \beta_{N_2} = 1$ | 16.11 |
| $\beta_{O_2} = \beta_{N_2} = 0.5$ | 19.22 |

| Process | E_j (eV) |
|--------------------|------------|
| N_2 dissociation | 9.76 |
| N_2 ionization | 15.58 |
| N ionization | 14.54 |
| O_2 dissociation | 5.16 |
| O_2 ionization | 12.07 |
| O ionization | 13.6 |



Results



RF POWER EFFECT

- The current increases with the power.

MASS FLOW EFFECT

- Below ~ 13.5 sccmAir, the current increases.
- Above ~ 13.5 sccmAir, the current saturates.

MAGNETIC FIELD EFFECT

- The effect depends on the mass flow and the rf power.
- Can either increase or decrease the current, or not have any effect.
- In general, it is detrimental for low rf power and beneficial for high rf power.

Results

RF POWER EFFECT

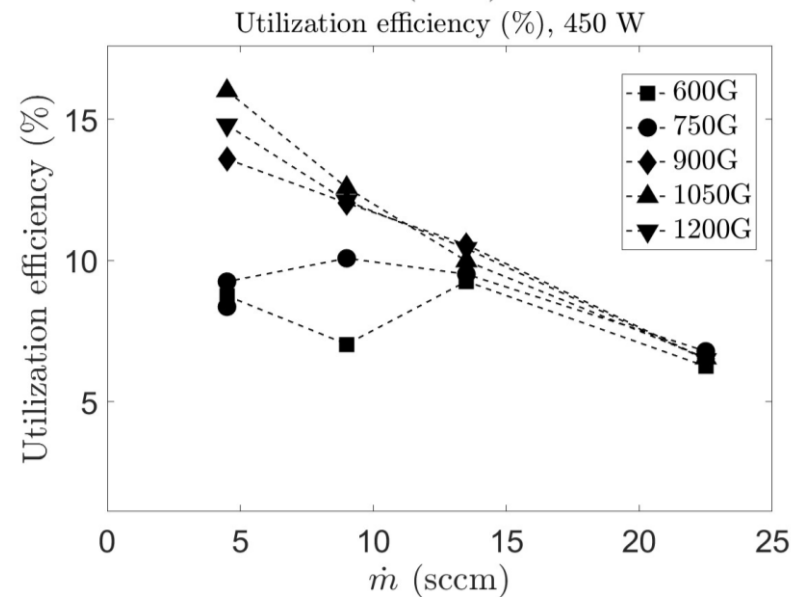
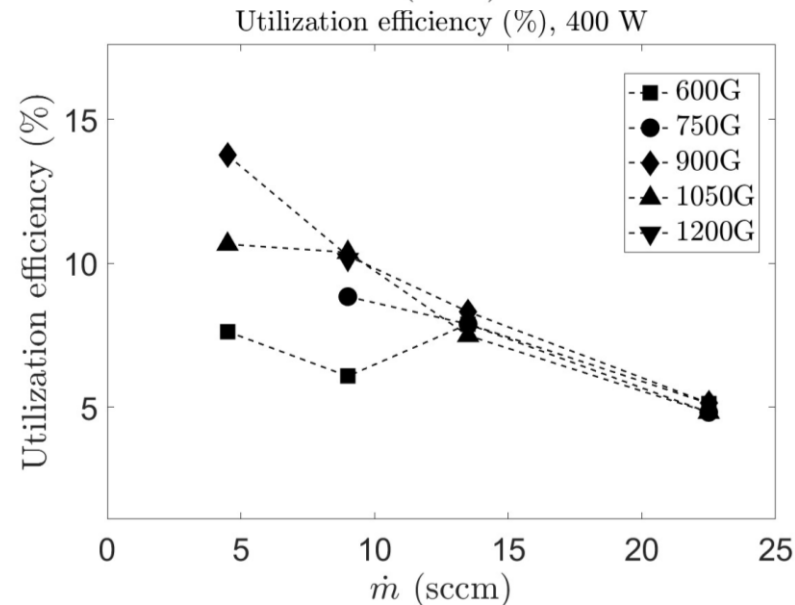
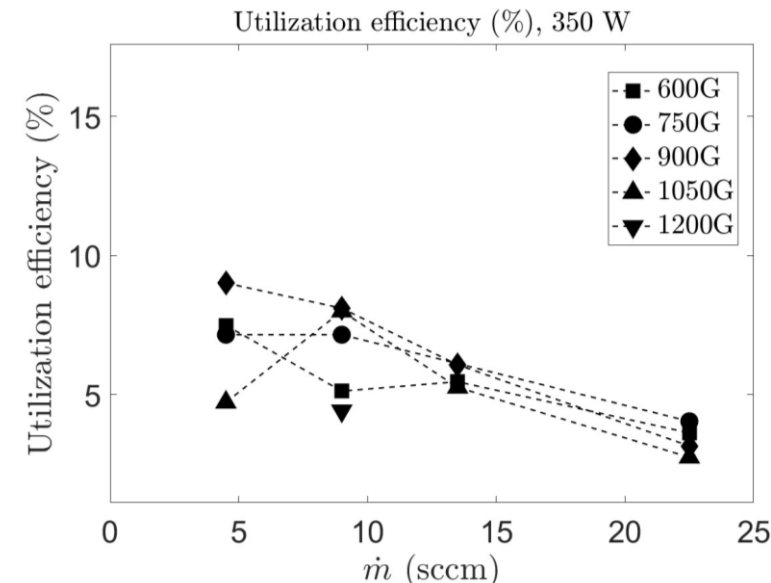
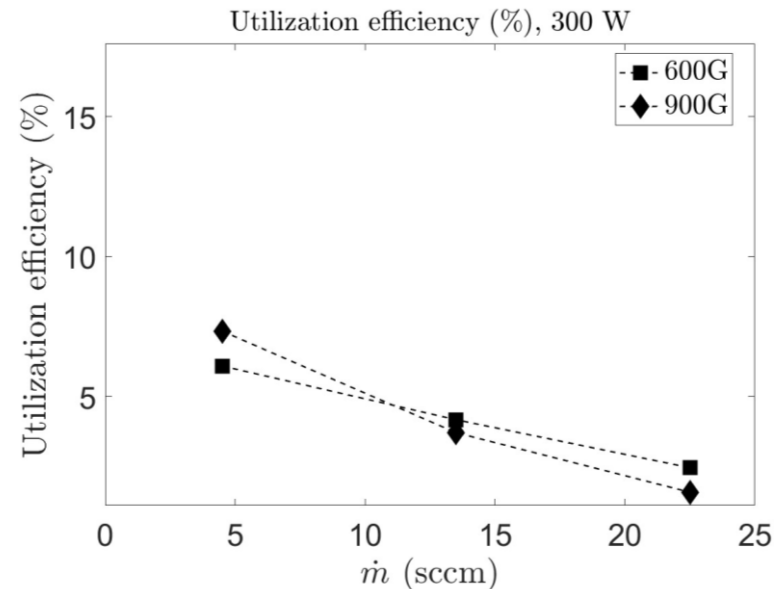
- The utilization efficiency increases with the power.

MASS FLOW EFFECT

- The utilization efficiency, in general, decreases with the flow.

MAGNETIC FIELD EFFECT

- At high values of mass flow does not seem to have an effect.
- At low values, the contribution is not well understood.



Results

RF POWER EFFECT

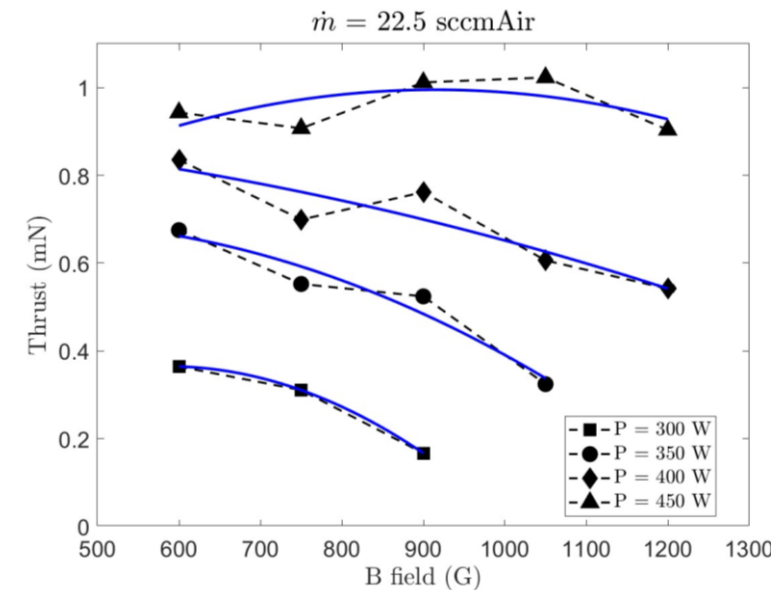
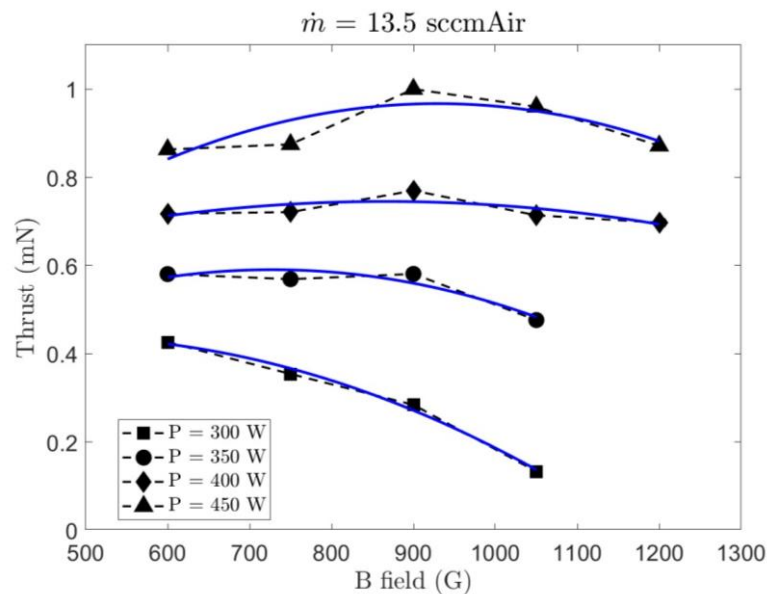
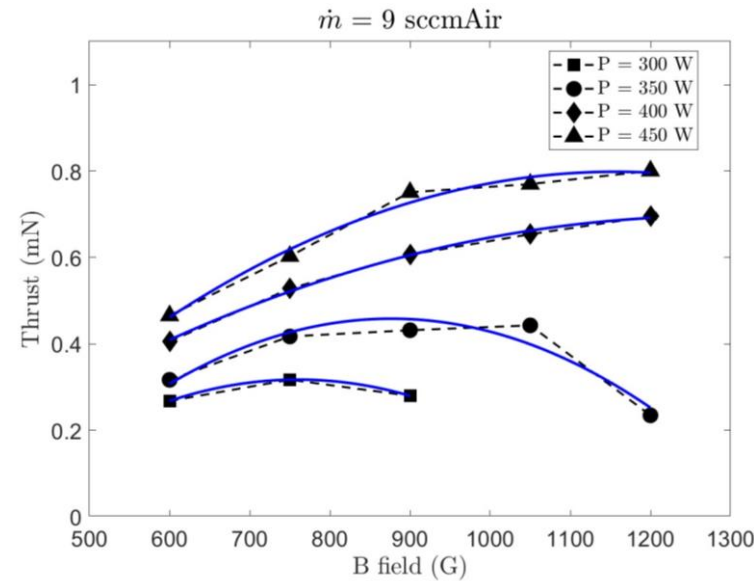
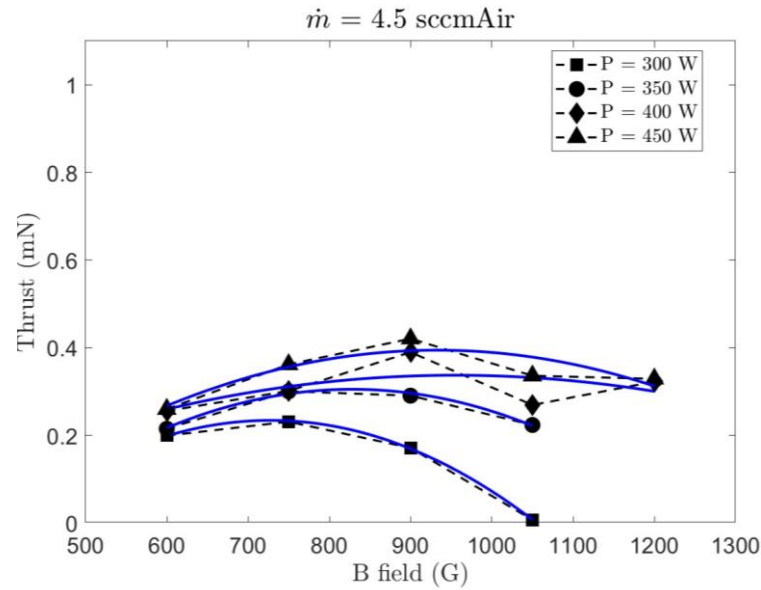
- The thrust increases always, typically in a linear way.

MASS FLOW EFFECT

- Below ~ 13.5 sccmAir, the thrust increases.
- Above ~ 13.5 sccmAir, the thrust saturates.

MAGNETIC FIELD EFFECT

- The effect depends on the mass flow and the rf power.
- Can either increase or decrease the thrust, or not have any effect.
- In general, it is detrimental for low rf power and beneficial for high rf power.



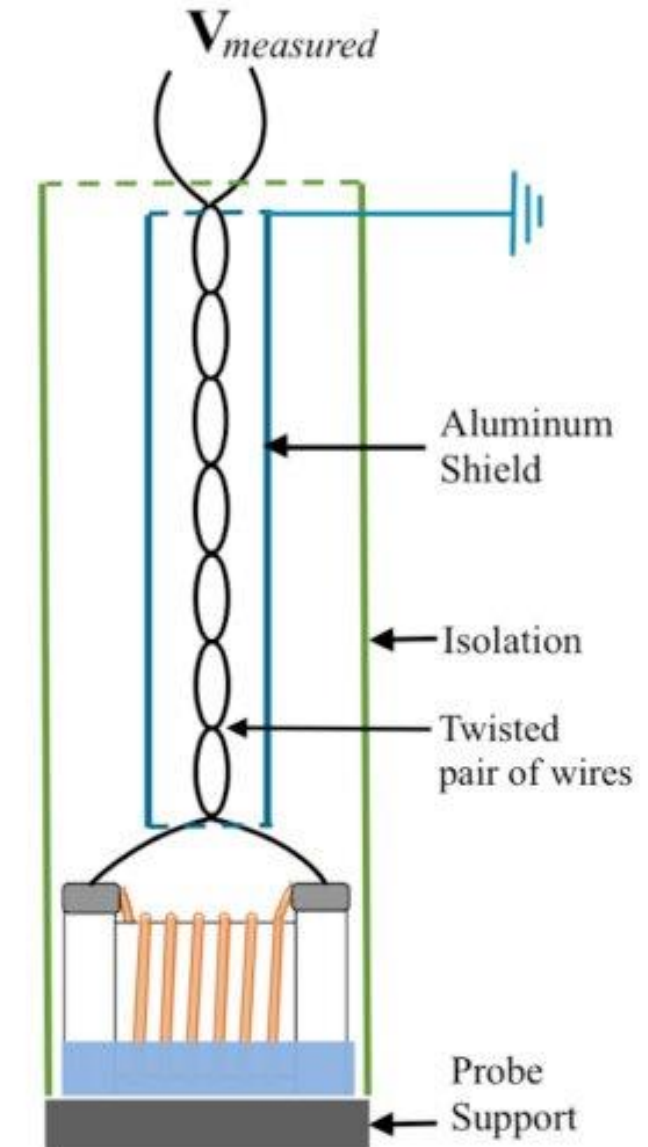
b-dot probe theory

➤ Objective

- ❑ Measure the helicon wave in the plume.
- ❑ Study the wave propagation and power coupling for different configurations.

➤ B-dot working principle

- ❑ Faraday Induction Law: $\epsilon = -\frac{d\Phi_B}{dt}$
- ❑ Ideally, $V_p = -NA\dot{B}_{tot}$
- ❑ Sensitivity, $|\beta| = \left| \frac{V_p}{i\omega B_{ext}} \right| = \frac{NAZ_0}{|Z_0 + i\omega L|}$

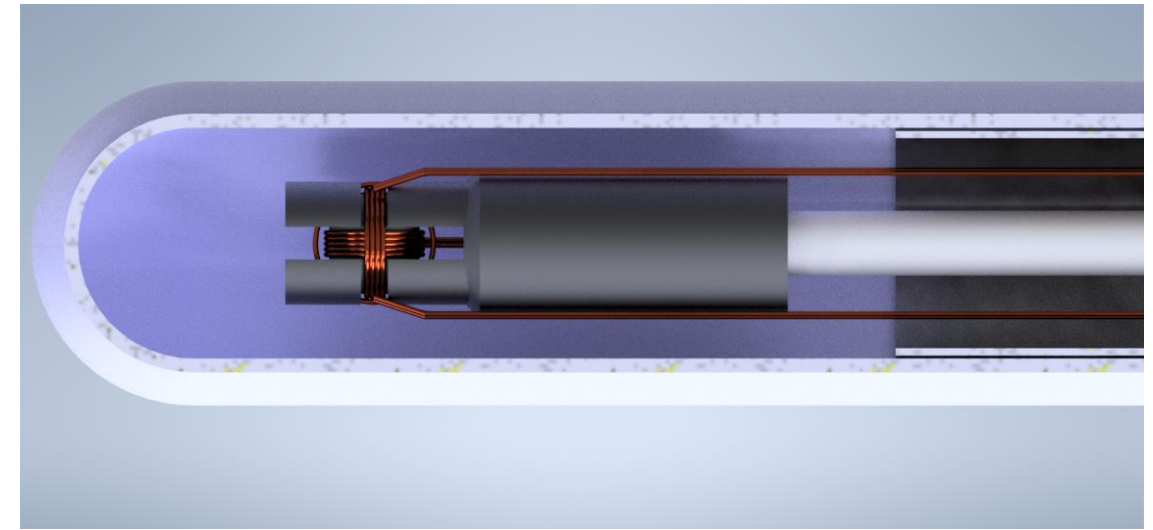
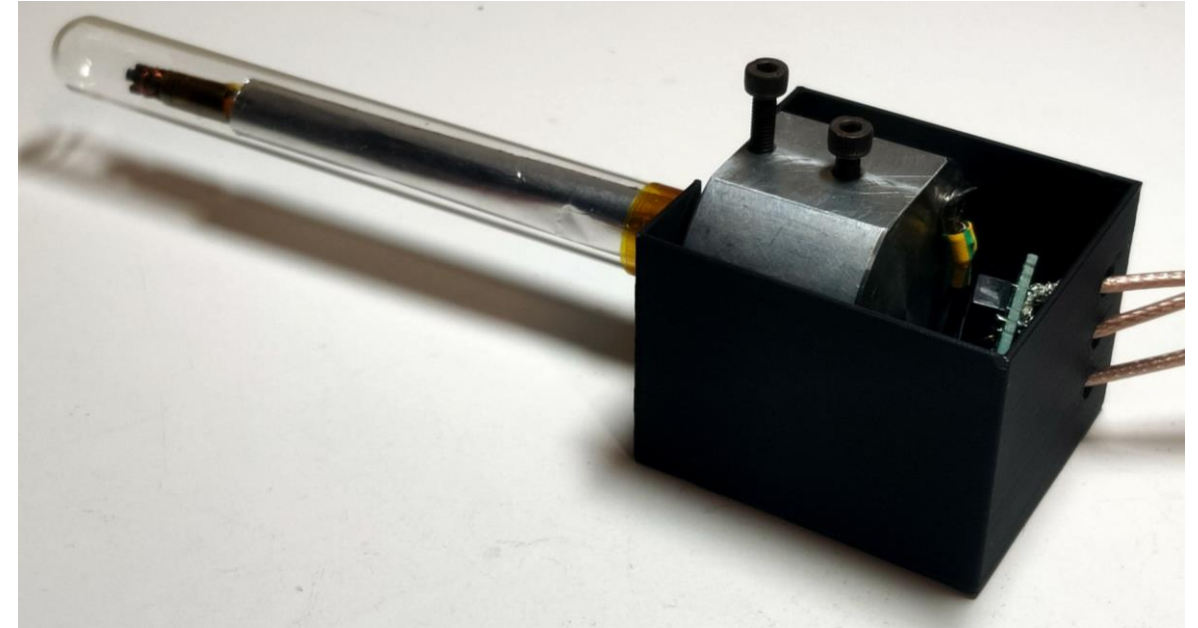
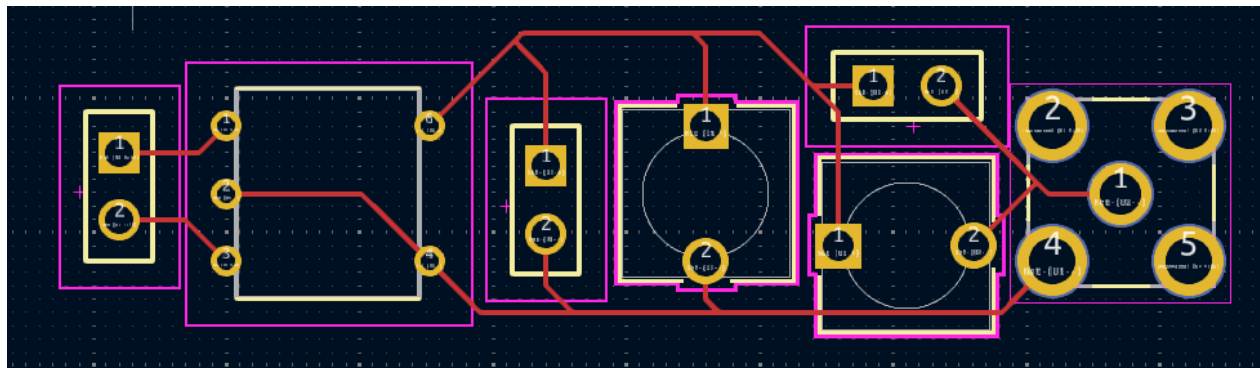


Manuel Azuara, et. al. (2019). Theoretical and Experimental Analysis for an Air-Breathing Pulsed Plasma Thruster

b-dot probe design

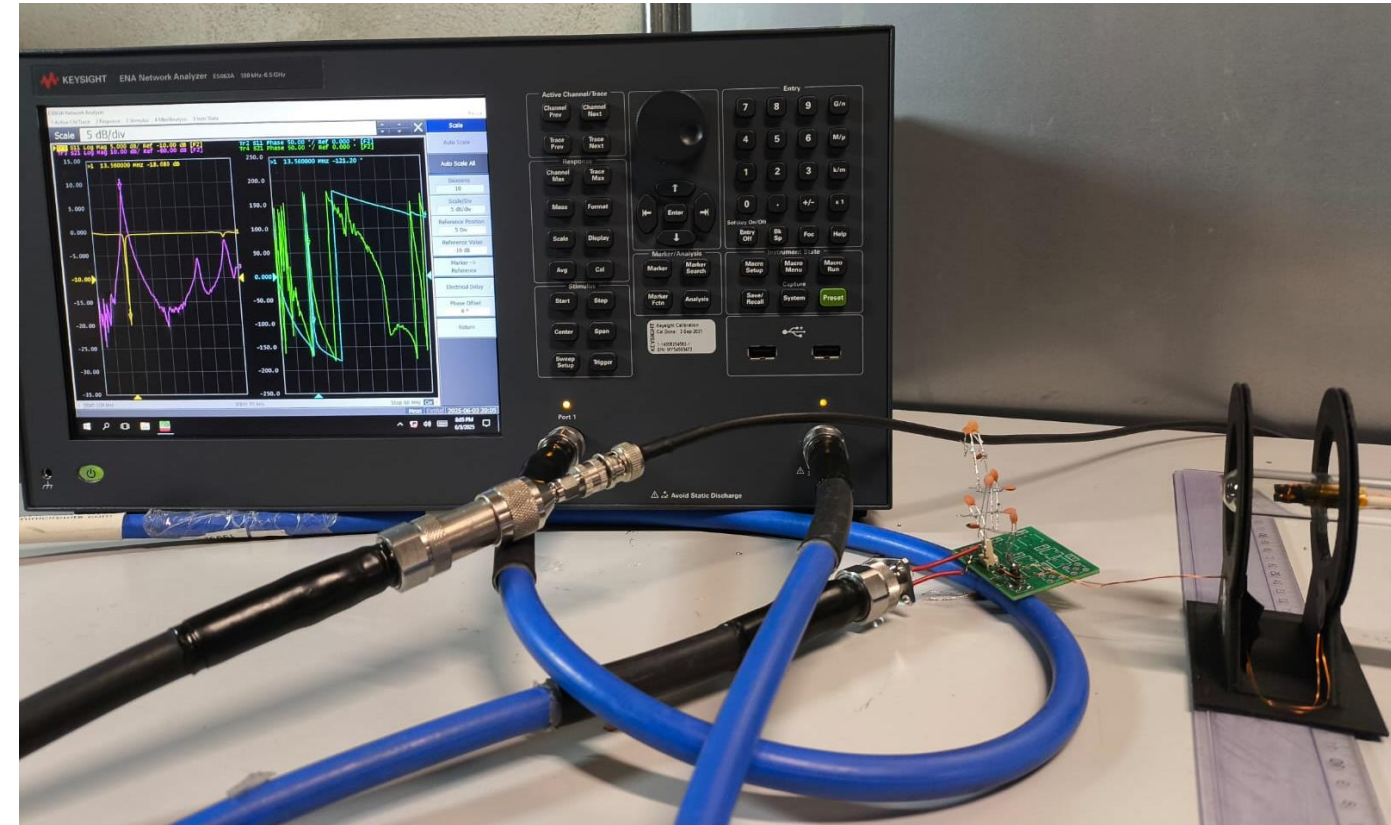
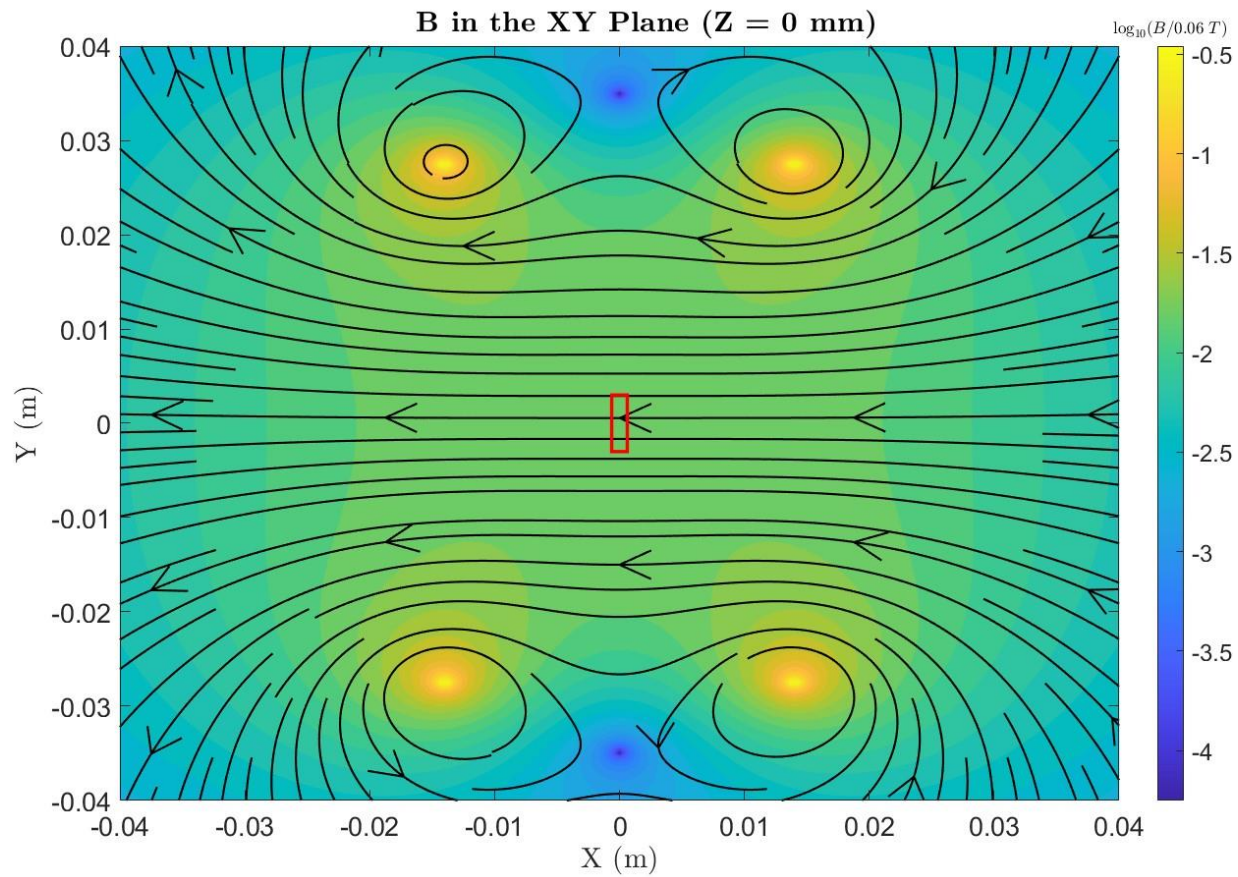
➤ Design & fabrication

- ❑ 3-axis b-dot probe: Designed so that every axis has the same sensitivity.
- ❑ $r < 3$ mm to ensure that the field is constant inside the loop.
- ❑ Aluminum foil as electric shield
- ❑ Electronics inside a Faraday Cage
- ❑ CTT for capacitive-pickup removal
- ❑ Dedicated L-type matching network
 - ❖ ~10% signal reflection at 13.56 MHz.



b-dot probe calibration

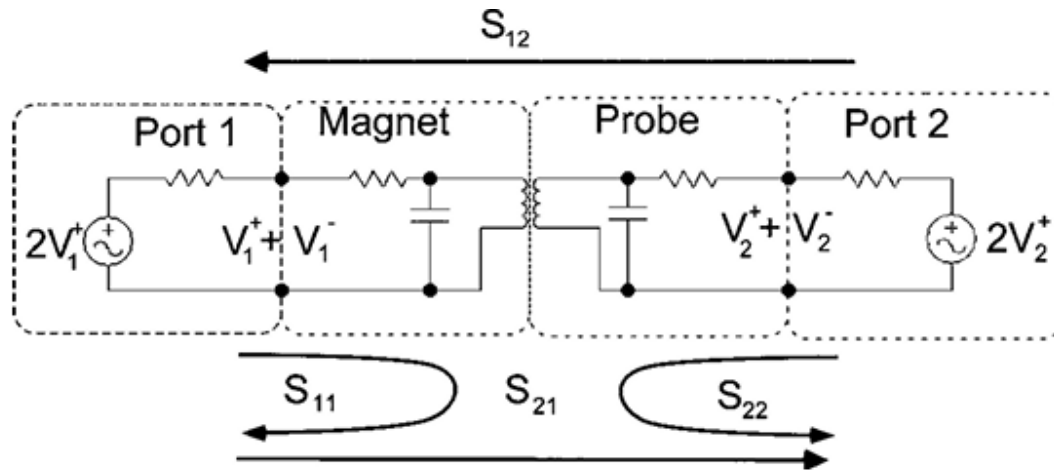
- ❑ Lots of lessons learnt. More complex than expected.
- ❑ Not trivial interaction with the calibration setup.



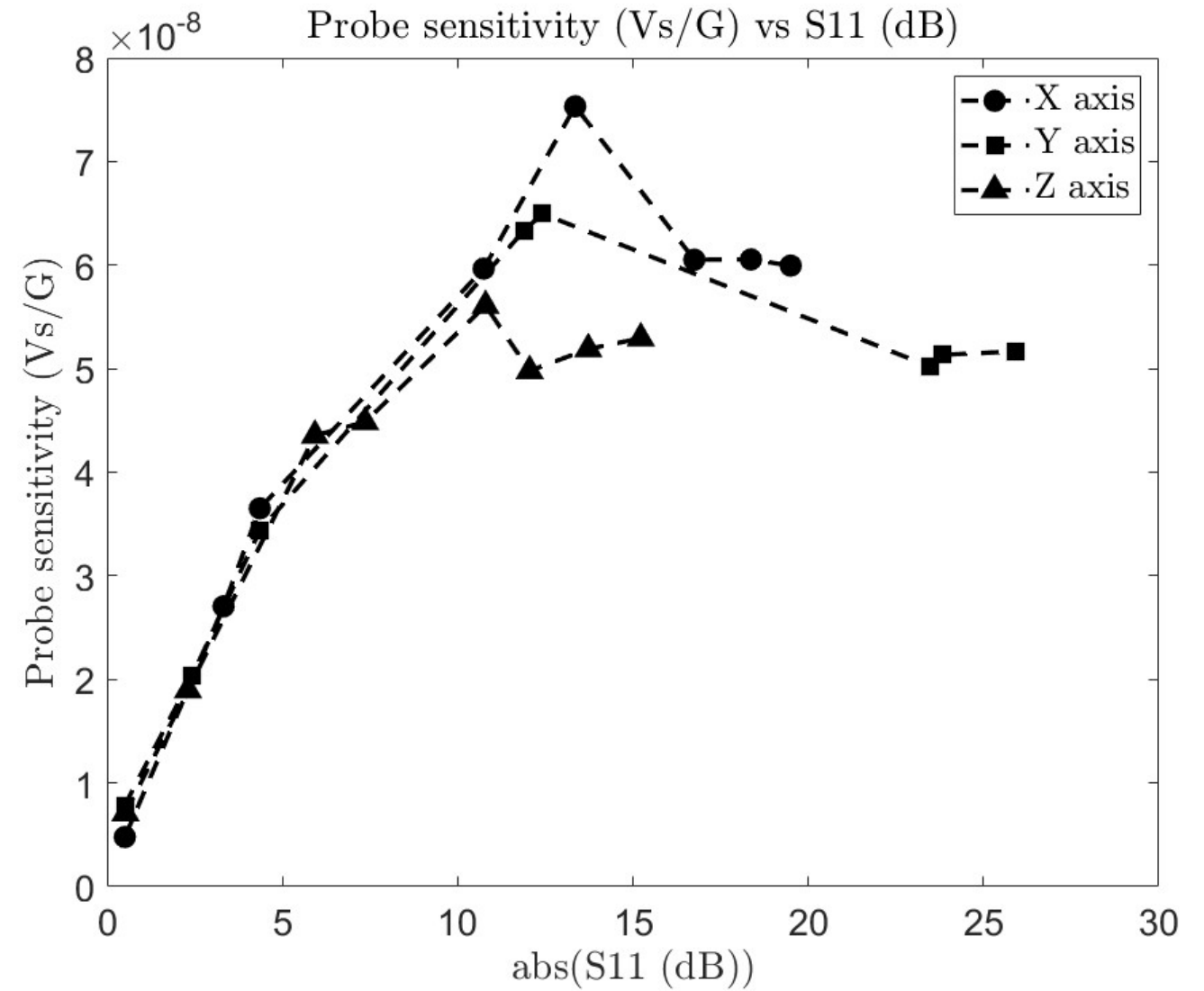
b-dot probe calibration

$$\beta = \frac{S_{21}Z_B}{2\pi i f \alpha (1+S_{11})e^{i\varphi}}$$

- Obtained sensitivity ~1 order of magnitude higher than the literature.



S. Messer, et. al. (2006). Broadband calibration of radio-frequency magnetic induction probes

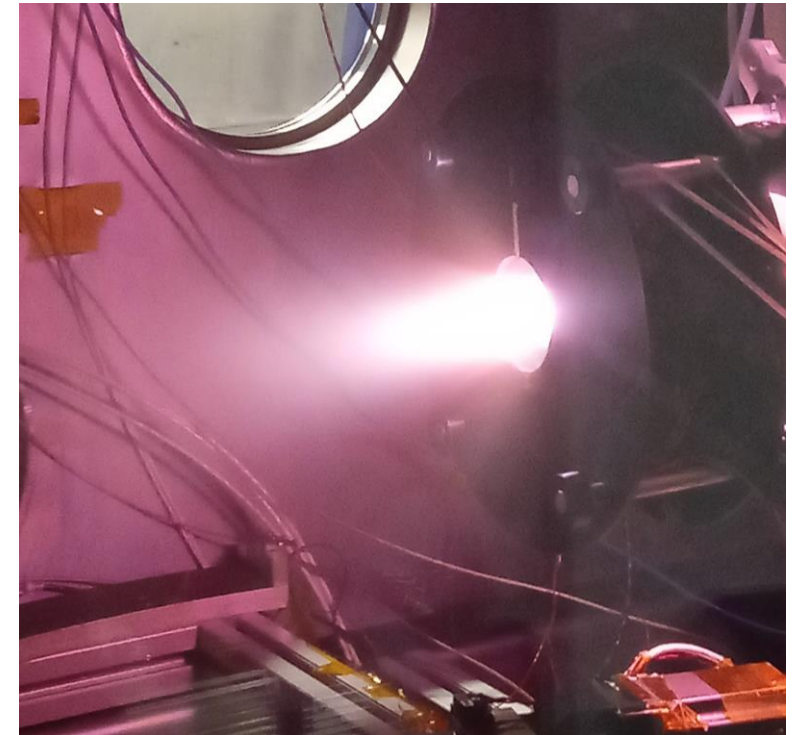


Conclusions & Future work

- First ABEP tests of our institution.
- First direct thrust measurements in an HPT operating with air.
- It might be necessary to have the ability to modify in orbit both the rf power and the magnetic field intensity.
- The calibration of a b-dot probe requires careful control of all the setup.



- Perform b-dot measurements for different conditions.
- 0-D global model for the composition of the plume.
- Use optical emission spectroscopy and the corresponding C-R model.
- Drag vs Altitude model.
- Optimize the thruster design to be used with Air.



Thank you! Questions?



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web: ep2.uc3m.es

EP² **uc3m**

BACKUP SLIDES

Results

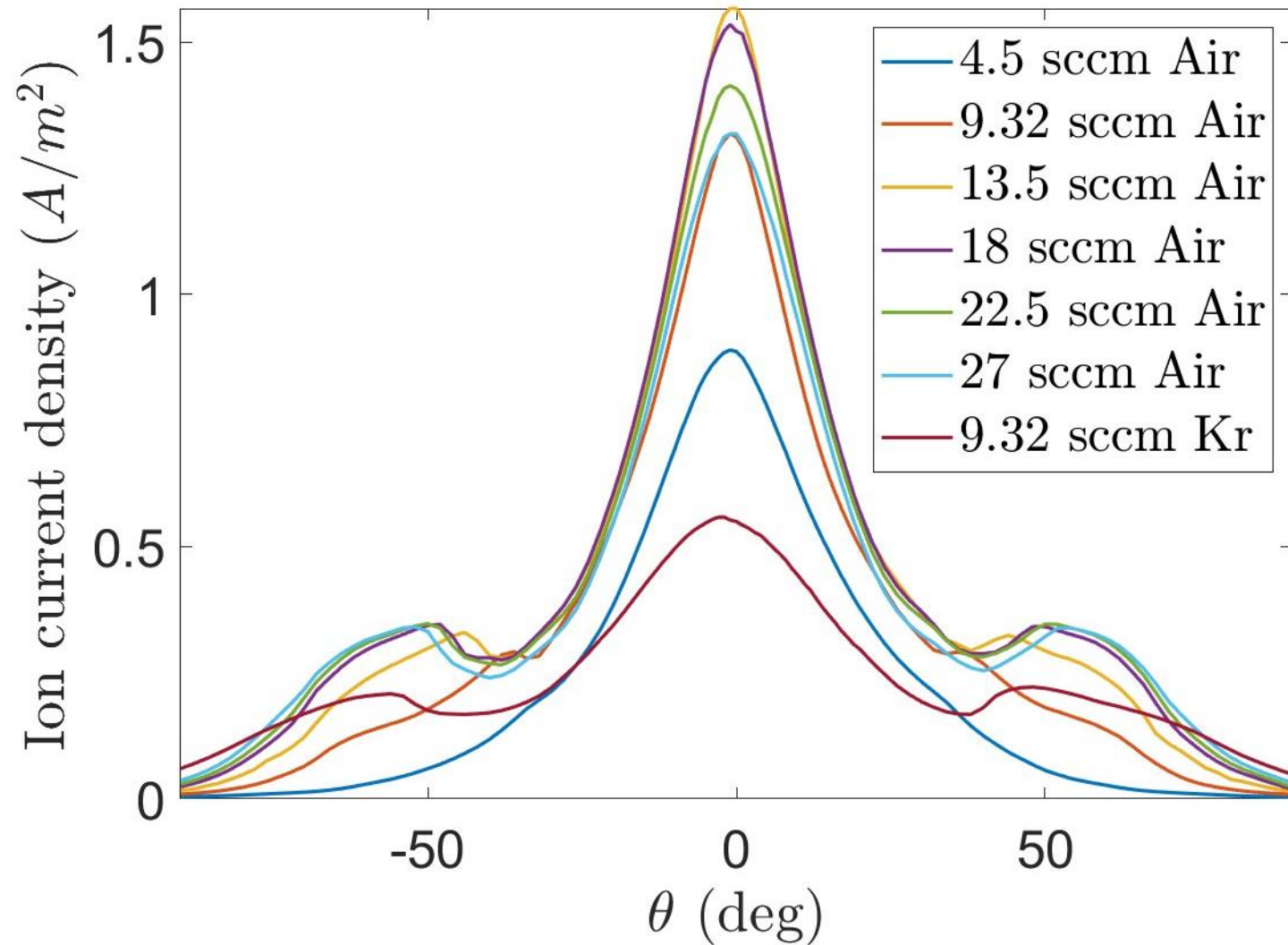
$P = 400 \text{ W}$, $B = 600 \text{ G}$

➤ Ion current density

- The center peak increases up to ~13.5 sccm Air.
- Increasing \dot{m} leads to an increase in the side lobes.
- More j_i than in the Krypton case for the same particle flow rate.



Confirms that the dissociation events probably dominate the plasma



Results

RF POWER EFFECT

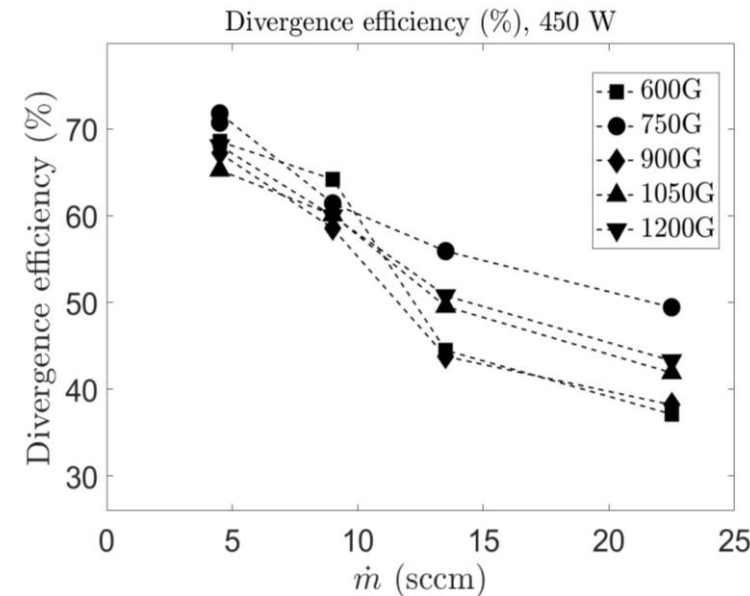
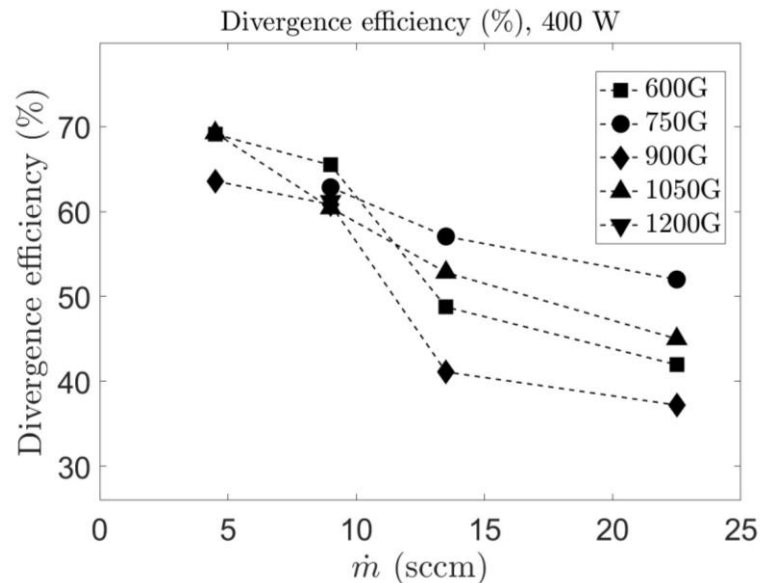
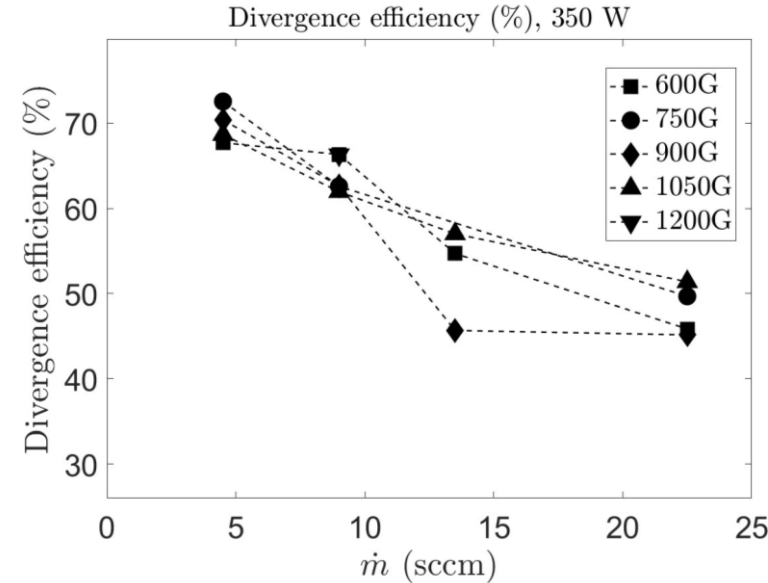
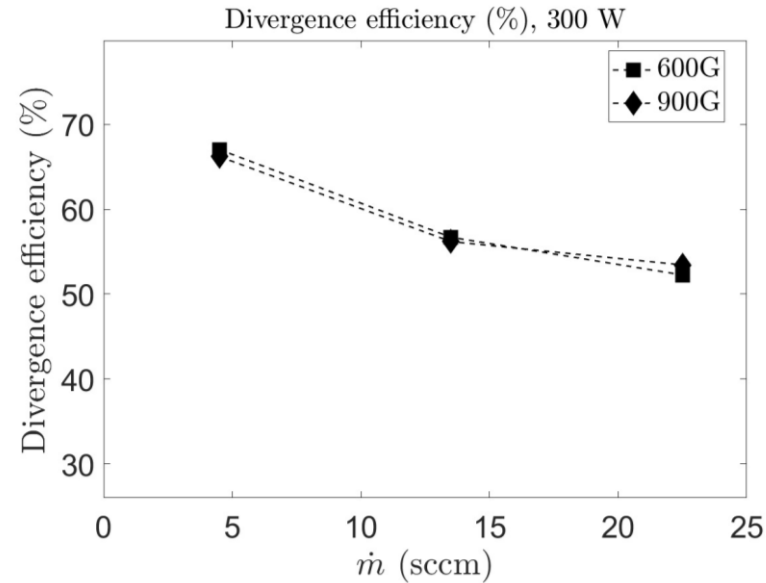
- Does not seem to have any remarkable impact, but it provokes a slight decrease.

MASS FLOW EFFECT

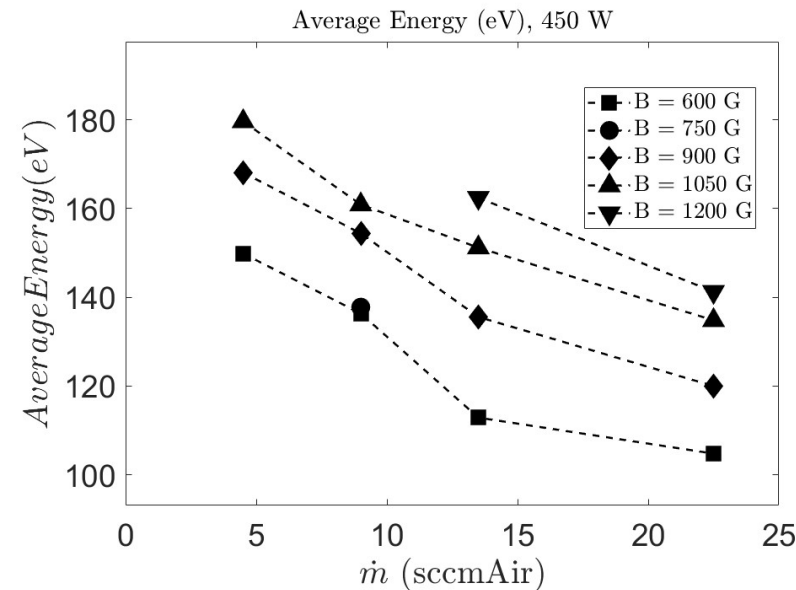
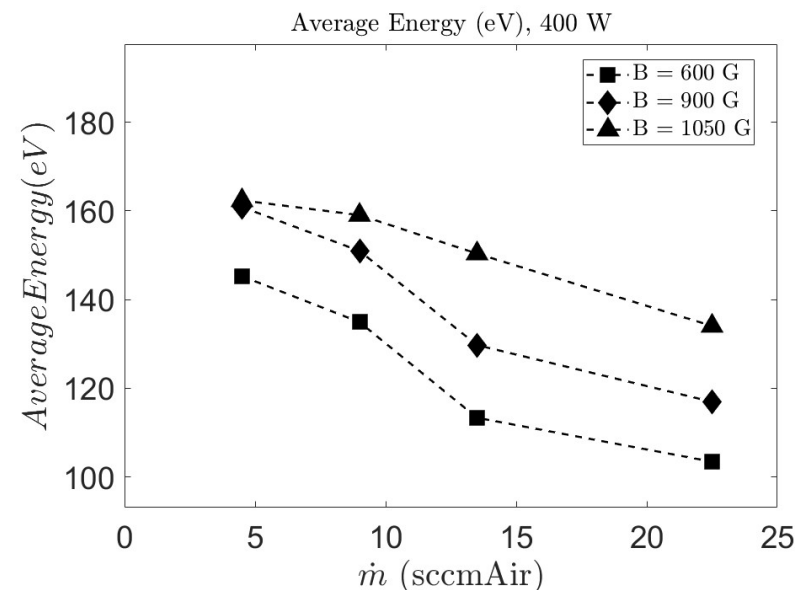
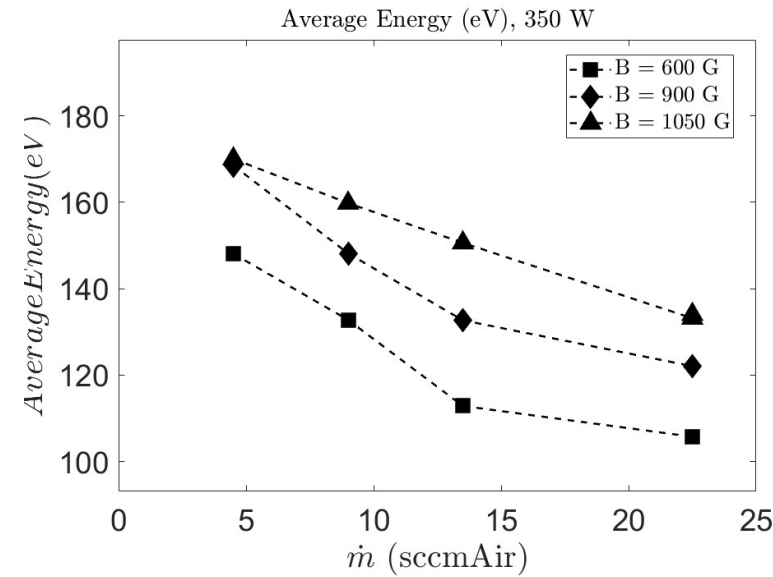
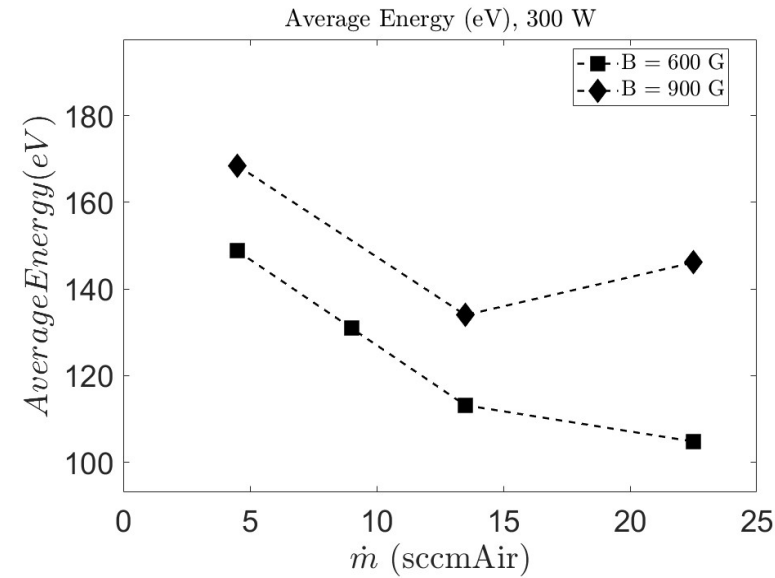
- Decreases with flow.

MAGNETIC FIELD EFFECT

- At low flows has little impact.
- At high flows, high powers has a great impact, although the relation is not trivial.



Results



RF POWER EFFECT

- Does not seem to have any remarkable impact.

MASS FLOW EFFECT

- Decreases with flow.

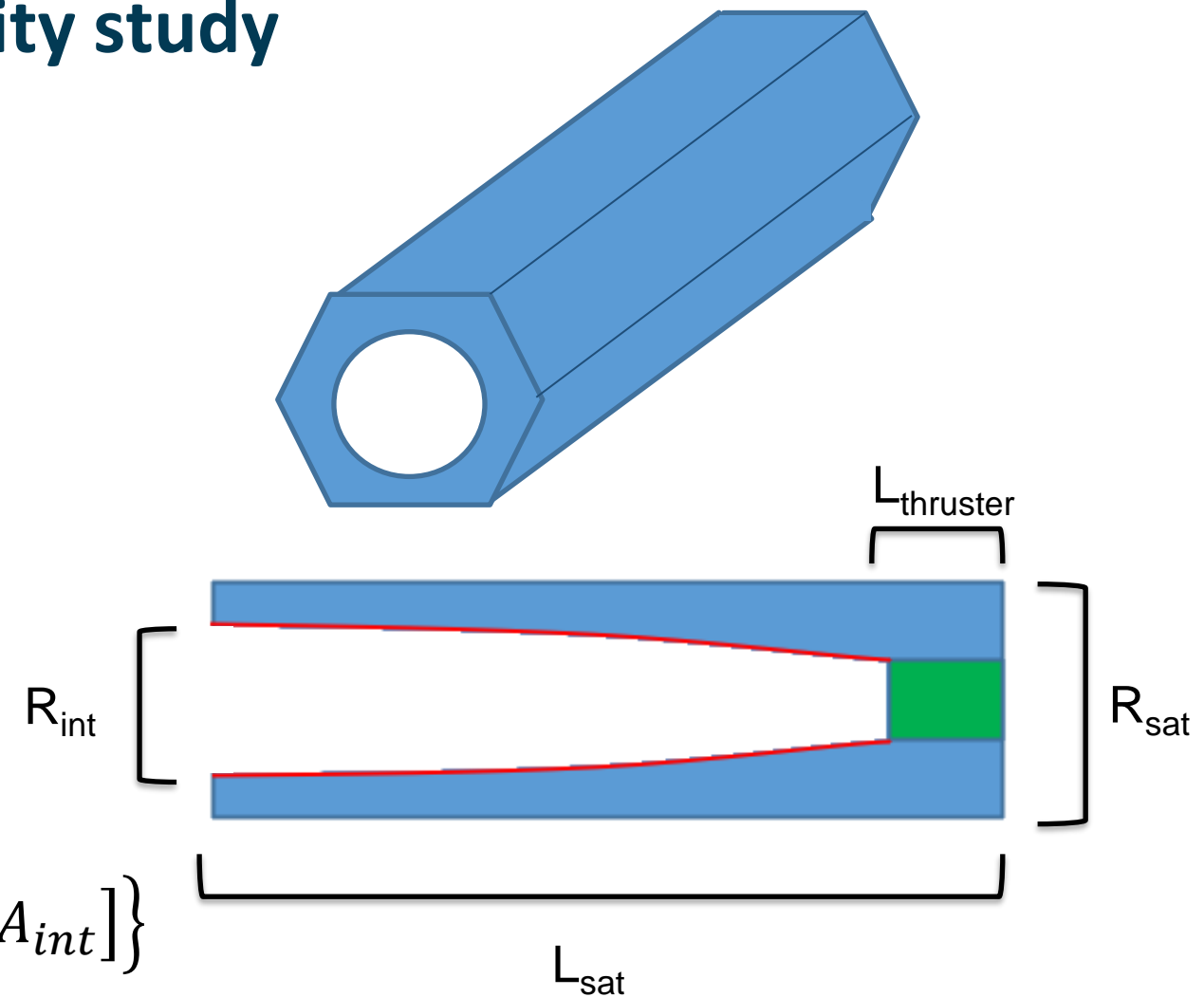
MAGNETIC FIELD EFFECT

- Increases the energy in all cases.

Initial feasibility study

➤ Drag vs Altitude Model

- $A_{int} = \frac{\dot{m}}{\eta_{int}\rho v}$
- $L_{sat} = \frac{A_{int}}{4\pi f_{length}} + L_{thruster}$
- $A_l = 2A_{panels} = \frac{P_{sat} + P_{rf} + P_{solenoid}}{\eta_{panel}E_{sun}}$
- $R_{sat} = \frac{A_l}{2\pi L_{sat}}$
- $A_{front} = \pi R_{sat}^2$
- $D = \frac{1}{2}\rho v^2 \left\{ C_{D_{par}} A_l + C_{D_{perp}} [A_{front} - (1 - \beta)A_{int}] \right\}$

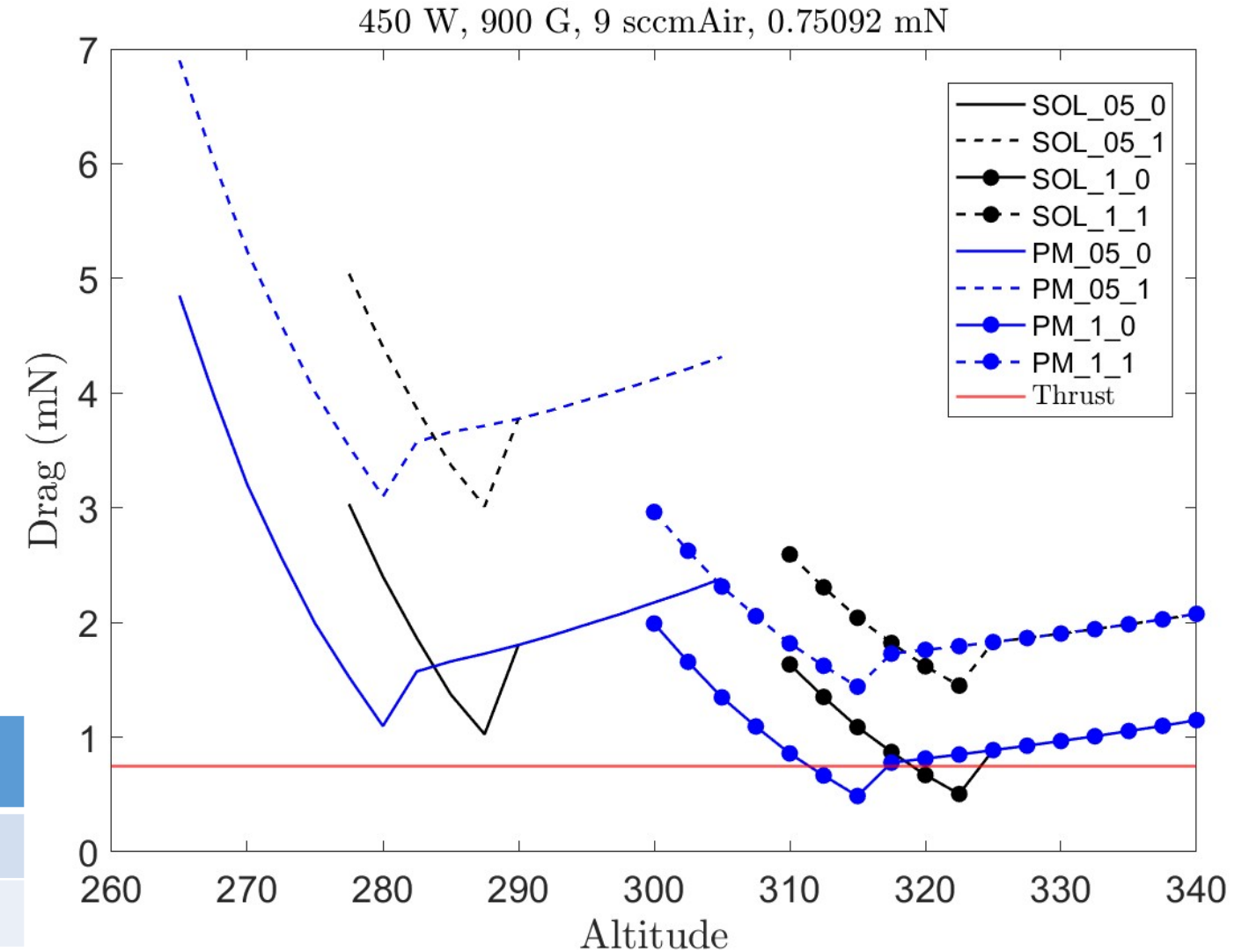


Initial feasibility study

➤ Input parameters

- ☐ $\eta_{int} \in [0.5, 1]$
- ☐ $\beta_{int} \in [0, 1]$
- ☐ Solenoid or Permanent Magnet
- ☐ $P_{sat} = 1 \text{ kW}$
- ☐ $\eta_{panel} = 0.3$
- ☐ Max dimensions -> Miura 5 fairing
 - ❖ $r_{max} = 0.825 \text{ m}$
 - ❖ $L_{max} = 2.97 \text{ m}$

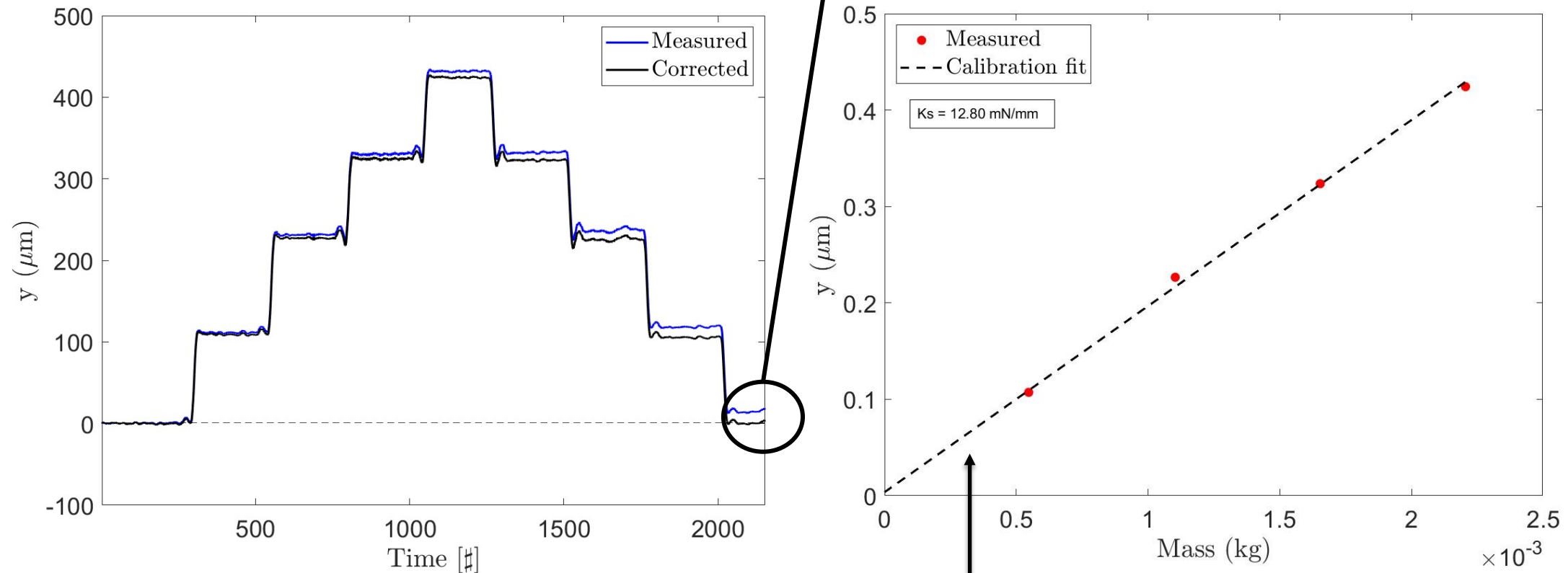
| Scenario | Power (W) | Mass flow (sccmAir) | Field (G) | Altitude (km) | Free volume (m ³) |
|----------|-----------|---------------------|-----------|---------------|-------------------------------|
| SOL_1_0 | 400 | 13.5 | 600 | 297.5 | 1.0245 |
| PM_1_0 | 450 | 13.5 | 900 | 292.5 | 0.8334 |



Experiments & Results

➤ Thrust calibration methodology

We have to correct the measurement to remove the thermal drift and other low-frequency oscillations



K_s is the slope of the mass-displacement plot

Experiments & Results

➤ Thrust measurement methodology

